AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions, and listings, of claims in the application:

- 1. (Currently Amended) Apparatus (10)-for establishing the positions of metal objects in a mixed input stream of both metal and non-metal objects, the apparatus comprising a differential metal-detecting coil (14A)-having a first coil portion (15) wound in a first sense and a second coil portion (16)-of generally similar shape and size to the first, wound in a second sense opposite to the first sense, and conveying means (11)-for moving objects with respect to, and past, the differential metal-detecting coil in a plane and in a direction with unit vector $\hat{\bf a}$, characterised in that the second coil portion is displaced from the first coil portion by a displacement $\bf B$ having a component in the plane in a direction with unit vector $\hat{\bf b}$, wherein $0 < \cos^{-1} \hat{\bf a} \cdot \hat{\bf b} < \frac{\pi}{2}$, and in that the apparatus further comprises analysing means (100)-a signal processor for analysing the form of the output voltage of the coil as a function of time to establish the position of said metal objects in a direction $\hat{\bf c}$ in the plane, where $\hat{\bf c}$ is defined by $\hat{\bf a} \cdot \hat{\bf c} = 0$.
- 2. (Original) Apparatus according to claim 1 wherein $\mathbf{B} \bullet \hat{\mathbf{a}} \ge t$, where t is the dimension of a coil portion in the $\hat{\mathbf{a}}$ direction, and $\frac{s}{2} \le \mathbf{B} \bullet \hat{\mathbf{c}} \le s$, where s is the dimension of a coil portion in a direction with unit vector $\hat{\mathbf{c}}$ defined by $\hat{\mathbf{a}} \bullet \hat{\mathbf{c}} = 0$.

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- 3. (Currently Amended) Apparatus according to claim 1—or claim 2 wherein the analysing means signal processor comprises means for is arranged to identifying distinguish voltages of different polarities, and forto ascribing associate voltages of a first polarity to with one coil portion and voltages of a second polarity, opposite to the first, to with the other coil portion.
- 4. (Currently Amended) Apparatus according to any preceding claim 1 and comprising a plurality of differential metal-detecting coils arranged in a linear array substantially in the $\hat{\mathbf{c}}$ direction.
- 5. (Currently Amended) Apparatus according to claim 4 and further comprising a single transmitter coil (13) arranged around the differential metal-detecting coils.
- 6. (Currently Amended) Apparatus according to claims 4 wherein the differential metal-detecting coils are each formed on a printed circuit board (PCB).
- 7. (Original) Apparatus according to claim 6 wherein the differential metaldetecting coils are formed on a single PCB.
- 8. (Original) Apparatus according to claim 7 wherein a single transmitter coil is formed on the PCB around the differential metal-detecting coils.

9. (Currently Amended) Apparatus according to claim 8 wherein the analysing means-signal processor comprises electronic hardware co-located with said coils on the single PCB.

Claims 10-12 (Cancelled)

- 13. (Currently Amended) A method of establishing the positions of metal objects in a mixed input stream of both metal and non-metal objects, characterised in that the method comprises use of apparatus according to any preceding claim 1.
- 14. (Currently Amended) A metal-detector array system comprising a plurality of differential metal-detecting coils, the array extending in a direction with unit vector $\hat{\mathbf{x}}$, and each metal-detecting coil having a first coil portion (15)-wound in a first sense and a second coil portion (16)-of generally similar shape and size to the first, wound in a second sense opposite to the first sense, characterised in that, in at least one metal-detecting coil, the second coil portion thereof is displaced from the first coil portion thereof by a displacement \mathbf{B} such that the two coil portions are substantially in the same plane and $0 < \cos^{-1} \hat{\mathbf{b}} \cdot \hat{\mathbf{x}} < \frac{\pi}{2}$ where $\hat{\mathbf{b}}$ is a unit vector defined by $\mathbf{B} \cdot \hat{\mathbf{b}} = |\mathbf{B}|$, and in that the system further comprises, in respect of that or those metal-detecting coil or coils, analysing means-a signal processor for analysing the form of the output voltage of the coil or coils as a function of time to establish the position, along the direction $\hat{\mathbf{x}}$, of metal

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objects when said objects are moving past the array substantially in a direction with unit vector $\hat{\mathbf{y}}$ where $\hat{\mathbf{x}} \bullet \hat{\mathbf{y}} = 0$.